

servo motor BMH, Lexium 32, 3.4Nm, 8000rpm, untapped shaft, without brake, IP54, 16 multiturn encoder, 3 phases

BMH0703P07A2A

Main

Device short name	вмн
Product or component type	Servo motor
Maximum mechanical speed	8000 rpm
Continuous stall torque	3.4 N.m for LXM32.D18N4 at 6 A, 400 V, three phase 3.4 N.m for LXM32.D18N4 at 6 A, 480 V, three phase
Peak stall torque	10.2 N.m for LXM32.D18N4 at 6 A, 400 V, three phase 10.2 N.m for LXM32.D18N4 at 6 A, 480 V, three phase
Nominal output power	1300 W for LXM32.D18N4 at 6 A, 400 V, three phase 1300 W for LXM32.D18N4 at 6 A, 480 V, three phase
Nominal torque	2.4 N.m for LXM32.D18N4 at 6 A, 400 V, three phase 2.4 N.m for LXM32.D18N4 at 6 A, 480 V, three phase
Nominal speed	5000 rpm for LXM32.D18N4 at 6 A, 400 V, three phase 5000 rpm for LXM32.D18N4 at 6 A, 480 V, three phase
Product compatibility	LXM32.D18N4 at 400480 V three phase
Shaft end	Smooth shaft
IP degree of protection	IP54 standard
Speed feedback resolution	32768 points/turn x 4096 turns
Holding brake	Without
Mounting support	International standard flange
Electrical connection	Rotatable right-angled connectors

Complementary

,	
Range compatibility	Lexium 32
[Us] rated supply voltage	480 V
Network number of phases	Three phase
Continuous stall current	3.91 A
Continuous power	1.68 W
Maximum current Irms	12.57 A for LXM32.D18N4
Maximum permanent current	12.57 A
Second shaft	Without second shaft end
Shaft diameter	14 mm
Shaft length	30 mm
Feedback type	Multiturn SinCos Hiperface
Motor flange size	70 mm

Number of motor stacks	3
Torque constant	0.87 N.m/A at 120 °C
Back emf constant	55.8 V/krpm at 120 °C
Number of motor poles	5.0
Rotor inertia	1.67 kg.cm ²
Stator resistance	2.65 Ohm at 20 °C
Stator inductance	4.175 mH at 20 °C
Stator electrical time constant	3.2 ms at 20 °C
Maximum radial force Fr	730 N at 1000 rpm 580 N at 2000 rpm 510 N at 3000 rpm 460 N at 4000 rpm 430 N at 5000 rpm 400 N at 6000 rpm
Maximum axial force Fa	0.2 x Fr
type of cooling	Natural convection
Length	186 mm
Centring collar diameter	60 mm
centring collar depth	2.5 mm
Number of mounting holes	4
Mounting holes diameter	5.5 mm
Circle diameter of the mounting holes	82 mm
Net weight	3 kg
Sizing reference	BMH0703P
Network number of phases	3
Accuracy error [angular]	4.8 °
Temperature copper hot	135 °C
Temperature magnet hot	100 °C
Temperature magnet rt	20 °C

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	11.5 cm
Package 1 Width	19.0 cm
Package 1 Length	40.0 cm
Package 1 Weight	3.655 kg
Unit Type of Package 2	P06
Number of Units in Package 2	36
Package 2 Height	105.0 cm
Package 2 Width	80.0 cm
Package 2 Length	60.0 cm
Package 2 Weight	138.58 kg

Contractual warranty

Warranty

18 months



Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing "Use Better, Use Longer, Use Again" campaign to extend product lifetimes and recyclability.

Environmental Data explained >

How we assess product sustainability >

☑ Environmental footprint	
Total lifecycle Carbon footprint	1435
Environmental Disclosure	Product Environmental Profile

Use Better

Packaging made with recycled cardboard	Yes
Packaging without single use plastic	No
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope)
SCIP Number	A7df881f-135f-4256-b8c2-ea55d4c9a151
REACh Regulation	REACh Declaration
PVC free	Yes

Use Again

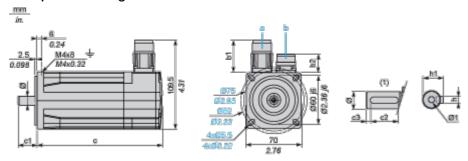
○ Repack and remanufacture									
End of life manual availability	No need of specific recycling operations								
Take-back	No								

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Dimensions Drawings

Servo Motors Dimensions

Example with Straight Connectors



- a: Power supply for servo motor brake
- b: Power supply for servo motor encoder
- (1) Shaft end, keyed slot (optional)

Dimensions in mm

_	Straight Rotatable angled connectors connectors		c (without c (with		c1 c2	c2	с3	h	h1	Ø	Ø1 for	
b1	b2	b1	b2	brake)	brake)							screws
39.5	25.5	39.5	39.5	186	225	30	20	5	5 h9	16 ⁺⁰ _ 0.13	14 k6	M5 x 17

Dimensions in in.

Straigh		Rotata angled connec		c (without	c (with brake)	1 01 1 02		с3	h	h1	Ø	Ø1 for screws
b1	b2	b1	b2	brake)								
1.55	1	1.55	1.55	7.32	8.85	1.18	0.78	0.19	0.20 h9	0.63 ⁺⁰ _ 0.0051	0.55 k6	M5 x 0.67

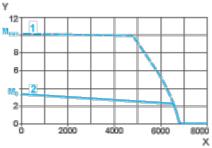
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Performance Curves

400 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive

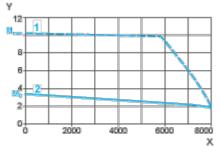


- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque

480 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive



- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque